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TIME VARYING SENSITIVITIES ON A GRID ARCHITECTURE

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We investigate the gains obtained by using GRID, an innovative web-based technology for parallel computing, in a Risk Management application. We show, by estimating a parametric Value at Risk, how GRID computing offers an opportunity to enhance the solution of computationally demanding problems with decentralized data retrieval. Furthermore, we also provide an analysis of the risk factors in the US market, by empirically testing, on the Fama and French database, a classic one factor model augmented with a time varying specification of beta.

Keywords: Time varying beta; Kalman filter; GRID computing; Value at Risk.

1. Introduction

The estimation and management of systematic risk has been one of the most studied topics in empirical finance. When analyzing risk in financial markets, the researchers face a serious trade-off between empirical accuracy and economic rigor. Currently, important research efforts are directed toward the development of advanced statistical methods to best fit the behavior of financial time series. At the other end of the research spectrum, some authors propose simple market models that convey strong economic background but are hardly successful in the empirical implementation.

With respect to the latter approach, standard OLS estimation of market model sensitivities produces a beta that is supposed to be constant, but there is no

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evidence of such statistical property. Indeed, time varying betas were studied by many authors.

In one of the earliest papers investigating the time series properties of risk sensitivities, Blume [4] found some evidence of mean reversion in the beta. In a following empirical work, Blume [5] showed stationarity for portfolios' betas and unstable behavior for single stocks' betas. In an explanation of these findings, the author claims that firms may tend to undertake riskier projects at the beginning of their life, leading to the founded mean reversion nature of beta for single stocks. Following these papers, Brenner and Smidt [10] proposed a non-stationary model, where the risk sensitivity of a stock is related with the value of the stock itself, showing further evidence of the time varying nature of betas. Furthermore, in an empirical work, Francis [21] provided an analysis, on a decade of CRSP data, confirming these findings.[1] On the other hand, some authors (e.g., Fabozzi and Francis [17] and Bos and Newbold [8]) show compelling evidence of time varying systematic risk due to micro and macro factors.

The introduction of more sophisticated econometric techniques in the financial literature also influenced the empirical research on risk sensitivities. In particular, following the seminal contributions by Engle [16] and Bollerslev [6] on modeling heteroskedasticity in time series, GARCH techniques are applied for modeling time varying risk sensitivities. In this strand of literature, Bollerslev *et al.* [7] apply a GARCH model to estimate a conditional CAPM model with the assumption of heteroskedasticity in the covariance between risky assets and market portfolios. By testing their assumption on the US market, the authors find strong support for their hypothesis of a time varying covariance matrix for assets' returns. In the same fashion, a Multivariate GARCH application to model time varying betas is developed in Braun *et al.* [9].[2] Alternatively, Schwert and Seguin [39] proposed and estimated a single factor model of portfolio returns heteroskedasticity: to estimate time varying monthly variances for size-ranked portfolios, they use predictions of aggregate stock return variances from daily data.

Most of the above studies have focused on the empirical test of stochastic nature of betas regardless of the "type" of the stock/portfolio investigated. The first step in this direction is in Ghysels [22], where the time varying nature of the systematic risk for several industry portfolios is investigated. Following this paper, Groenewold and Fraser [25] applied a Kalman filter estimation to Australian industry portfolios, and argued that industrial sectors are divided into two classes, one with time varying

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[1]Further, evidence on the US market is presented in Sunder [41], where the null hypothesis of market risk stationarity is tested against a random walk specification, and in Ohlson and Rosenberg [32], where an ARMR(1,1) model is proposed and tested on an equally weighted portfolio based on 50 years of CRSP data. In a following empirical work, Collins *et al.* [13] confirmed the autoregressive nature of risk sensitivities found in Ohlson and Rosenberg [32], with a detailed comparison of four different model specifications.

[2]Furthermore, the time varying nature of systematic risk is confirmed on several international markets in Giannopoulos [23].

risk sensitivities and the other one with relatively stable behavior.[3] A Kalman filter estimation is also performed by Black *et al.* [3] to analyze the performance of UK Unit trusts in the 1980s.

Our paper is closely related with the presented empirical literature on the estimation of time varying risk sensitivities, and it is making a step toward the implications of a time varying risk for a Risk Management application.

It is well known how the computational burden implied by Risk Management applications, either parametric or non-parametric models, is dramatically increased (see Jorion [28]). While the GRID computing, a new web-based technology for parallel computing, has moved ahead the computational frontier for researchers and practitioners in the engineering disciplines, up to now the finance community has not exploited its advantages.

This paper aims to fill a part of this gap by investigating the use of GRID computing in a Risk Management application, and by providing the first numerical evidence of important efficiency improvement for financial applications by using this technology. Our main contribution is to propose a Value at Risk application on several stock portfolios based on the estimation on a GRID computing environment, showing its potential for enhancing the solution of computationally demanding problems with decentralized data retrieval. The proposed approach is based on a time varying nature of the risk factors and is tested on the US market by using a a Kalman filter approach augmented with a Genetic Algorithm for the log-likelihood optimization. First, this allows us to investigate the risk sensitivity for a broad class of portfolios as well as for a wide range of stocks with different characteristics,[4] and second, we are able to provide a detailed empirical analysis of the improvements attainable within a GRID architecture for a Risk Management application.

The remainder of the paper is organized as follows. In Sec. 2, we present the market model framework as a theoretical background to the empirical investigation. Section 3 introduces the data set used in the empirical part and provides descriptive statistics of the analyzed stock portfolios. In Sec. 4, we describe the estimation procedure and discuss the results of the empirical investigation on the US stock market. In Sec. 5, we implement the risk management application and Sec. 6 concludes.

2. Theoretical Background

In this section we review the theoretical framework for our empirical estimation. Starting from the Arbitrage Pricing Theory (APT) (cf. [12, 36, 38]), which models

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[3]Interestingly enough, Groenewold and Fraser [25] run also a recursive regression and a rolling regression on the same data, finding inconsistencies in the obtained results. To investigate these results, Brooks *et al.* [11] performed a horse race amongst three different model specifications on the same market. Based on both in-sample and out-of-sample forecast errors, they found overwhelming support for the Kalman filter approach.

[4]To economize space and keep the paper readable, results on single stocks are available upon request.

the statistical evidence that asset payoff tends to move together, we derive a simple market model for stock returns. Standard assumptions of APT are that markets are competitive and frictionless and that returns are generated according to

$$R = a + Bf + \epsilon \tag{2.1}$$

where R is an $(N \times 1)$ vector of returns, a is the $(N \times 1)$ vector of intercepts of the factor model, B is the $(N \times N)$ matrix of factor sensitivities, f is the $(N \times 1)$ vector of factors, and ϵ is the $(N \times 1)$ vector of disturbances, with $\epsilon \sim N(0, \Sigma)$ Σ diagonal.

If a risk free asset exists and adopted factors are traded portfolios, exact factor pricing holds. Throughout the paper we assume that a risk free asset is traded and that the market portfolio is the pricing factor. Therefore, the pricing model can be expressed using a market portfolio as a factor:

$$R_{it}^e = \beta_i R_{mt}^e + \epsilon_{it}, \tag{2.2}$$

where the superscript e indicates excess returns.

As a departure from the classical APT models we consider time varying factor sensitivities. More specifically, we assume a mean reverting process for the beta:

$$\beta_{it} = \overline{\beta_i} + \alpha_i(\beta_{it-1} - \overline{\beta_i}) + \sigma_i \varepsilon_t^i, \tag{2.3}$$

where $\overline{\beta_i}$ is the unconditional mean of the sensitivity relative to the asset i, σ_i is its conditional volatility, α_i is the mean reversion parameter, and the error $\varepsilon_t^i \sim N(0,1)$ is i.i.d. Thus, considering both Eqs. (2.2) and (2.3), the proposed model for the asset returns is

$$\begin{aligned} R_{it}^e &= \beta_{it} R_{mt}^e + \epsilon_{it}, \\ \beta_{it} &= \overline{\beta_i} + \alpha_i \left(\beta_{it-1} - \overline{\beta_i} \right) + \sigma_i \varepsilon_t^i. \end{aligned} \tag{2.4}$$

3. Data

In this section we present and describe the main features of the financial series employed in this study. Our empirical exercise is mainly based on the portfolios formed on Size (SIZE), Earning Price (E-P), Dividend Price (D-P), and Industry (IND) from Kenneth French's website.

SIZE portfolios are constructed at the end of each June using the June market equity and NYSE breakpoints. The Market Value is computed as price times shares outstanding. The available sample period is from July 1926 to December 2004.

D-P portfolios are formed on dividend price ratios at the end of each June using NYSE breakpoints. The dividend yield used in June of year t is the total dividends paid from July of $t-1$ to June of t per dollar of equity in June of t. The available sample period is from July 1927 to December 2004.

E-P Portfolios are constructed with the earning price ratio at the end of each June using NYSE breakpoints. The earnings used in June of year t are total earnings before extraordinary items for the last fiscal year end in $t-1$. The sample period covers July 1951 to December 2004.

Table 1. Descriptive statistics of financial series.

	Qtn 1	Qtn 2	Qtn 3	Qtn 4	Qtn 5
Panel A: size portfolios					
Entire sample					
Mean	1.39%	1.26%	1.20%	1.12%	0.93%
Std	9.33%	7.74%	7.07%	6.34%	5.25%
Postwar sample					
Mean	1.27%	1.24%	1.19%	1.16%	1.00%
Std	5.88%	5.47%	5.02%	4.72%	4.11%
*Panel B: E-P portfolios***					
Postwar sample					
Mean	0.84%	1.01%	1.10%	1.33%	1.46%
Std	4.90%	4.19%	4.23%	4.16%	4.71%
*Panel C: D-P portfolios**					
Entire sample					
Mean	0.96%	0.98%	0.94%	1.12%	1.10%
Std	5.98%	5.36%	5.49%	5.49%	6.11%
Postwar sample					
Mean	1.04%	1.07%	1.02%	1.19%	1.17%
Std	5.07%	4.44%	4.18%	4.00%	3.88%
	Manuf	Utils	Shops	Money	Other
Panel D: industry portfolios					
Entire sample					
Mean	1.03%	0.97%	0.96%	1.13%	0.97%
Std	5.47%	5.59%	5.75%	5.86%	6.49%
Postwar sample					
Mean	1.08%	1.02%	1.02%	1.23%	1.08%
Std	4.45%	4.08%	5.27%	5.04%	4.83%

Note: This table reports the mean and the standard deviation of the analyzed stock portfolios. The portfolios are from the Kenneth French website. All returns are monthly value weighted.
*Sample starting July 1927.
**Postwar data available from July 1951.

Finally the selected Industry portfolios are Manufacturing (SIC codes 2000-3999), Utilities (SIC codes 4900-4999), Shops (SIC codes 5000-5999, 7000-7999), Money and Finance (SIC codes 6000-6999), and Others.[5]

In order to better understand the empirical exercise, it is worth looking briefly at the basic characteristics of the analyzed market. Table 1 presents, for each of the analyzed portfolios, the mean and the standard deviation of the return time series. Panel A of Table 1 presents the descriptive statistics for the SIZE based portfolios. During the entire sample period the SIZE portfolio, based on the lowest quintile, outperforms by 46 basis points the portfolio based on the highest quintile, confirming the well documented size effect (see [20, 27, 40] among others). Panels

[5]A detailed description, along with the data, is available at http://mba.tuck.dartmouth.edu/pages/faculty/ken.french.

B and C of Table 1 show the descriptive statistics for the E-P and D-P based portfolios, respectively. In these cases, the portfolios based on the highest quintile systematically outperform the portfolios based on the lowest quintile, confirming the well known value effect. (cf. for example, Basu [2]). Finally, Panel D, Table 1, presents the descriptive statistics of the chosen industry portfolios. During the entire sample the portfolios seem to have a similar volatility-return profile, except the Money portfolios that slightly outperform the others.

4. Empirical Results

4.1. *Estimation procedure*

Given the unobservable nature of the risk factors, the estimation of the model presented in Eq. (2.4) is performed using a Kalman filter, where the observation equation and the state equation are specified as follows:

$$
\begin{aligned}
Y_t &= \Phi_t S_t + R\epsilon_t, \\
S_t &= A + FS_{t-1} + Qv_t.
\end{aligned}
\tag{4.1}
$$

In the above state-space form, Y_t is a column vector that stores the asset returns observed at time t; Φ_t is a column vector of the observable risk factor (in our case the market index), and S_t is a column vector of the unobservable risk factor sensitivities. In our model specification, the unobservable variables are supposed to follow a simple mean reverting autoregressive process. Thus, A and F are, respectively, column vectors of the unconditional means and a [assets × assets] diagonal matrix with the autoregressive parameters on the diagonal. Furthermore, Q and R are diagonal matrices of the volatilities of the unobservable and the observable variables, respectively. Finally, ϵ_t and v_t are column vectors of error terms with a $N(0, I)$ probability distribution. To guarantee and facilitate the correct estimation of the process parameters some restrictions are imposed. For all processes, the domain of the diffusion terms is restricted to be positive. Once the restriction is imposed, the Kalman filter is performed.

   To implement the algorithm, we follow closely the procedure in Hamilton [26]. First, we initialize the state-vector S_t with its expected value:

$$
S_{1|0} = A + FS_0,
\tag{4.2}
$$

where S_0 contains the guessed starting values of the state variables. The associated mean squared error (MSE, i.e., the variance covariance matrix of the initialized state vector) can be computed as

$$
P_{1|0} = FP_{1|0}F' + Q'Q.
\tag{4.3}
$$

By using the well-known result from matrix algebra, $\text{vec}(ABC) = [(C' \otimes A)\text{vec}(B)]$, we can easily compute the MSE as

$$
\text{vec}(P_{1|0}) = [I - F \otimes F]^{-1}\text{vec}(Q'Q).
\tag{4.4}
$$

The second step of the algorithm consists in forecasting the observable variables and updating the Kalman filter. With the updates it is then possible to calculate the new estimates for the state variable vector and its variance covariance matrix. The forecast of the Y_t vector is computed as

$$Y_{t|t-1} = \Phi S_{t|t-1}, \tag{4.5}$$

with an estimation forecast error equal to:

$$\xi_t = \Phi(S_t - S_{t|t-1}), \tag{4.6}$$

and a covariance matrix of the estimation forecast error equal to:

$$\mathbb{E}\left[\xi_t'\xi_t\right] = \Phi P_{t|t-1}\Phi' + R'R. \tag{4.7}$$

Once we have calculated the estimation forecasts and the relative estimation errors, we can update the Kalman filter via

$$
\begin{aligned}
S_{t|t} &= S_{t|t-1} + P_{t|t-1}\Phi'(\Phi P_{t|t-1}\Phi' + R'R)^{-1}\xi_t, \\
P_{t|t} &= P_{t|t-1} - P_{t|t-1}\Phi'(\Phi P_{t|t-1}\Phi' + R'R)^{-1}\Phi P_{t|t-1}.
\end{aligned}
\tag{4.8}
$$

Thus, new estimates for the state variable vector and its variance covariance matrix can be calculated as

$$
\begin{aligned}
S_{t+1|t} &= A + F S_{t|t}, \\
P_{t+1|t} &= F P_{t|t} F' + Q'Q.
\end{aligned}
\tag{4.9}
$$

The last step of the Kalman filter procedure is to compute and maximize the log-likelihood function. In our model the log-likelihood to be maximized is

$$\mathcal{L}_T = \sum_{t=1}^{T} \mathcal{L}_t = \sum_{t=1}^{T}\left((2\pi)^{-\frac{1}{2}}|\Phi P_{t|t-1}\Phi' + R'R|^{-\frac{1}{2}}e^{[-\frac{1}{2}\xi'(\Phi P_{t|t-1}\Phi' + R'R)^{-1}\xi]}\right). \tag{4.10}$$

In order to maximize the expression in Eq. (4.10) we choose to implement a Genetic Algorithm (GA) procedure. There are several features which make GA more suitable then other optimization algorithms for our purpose. First of all it is usually more robust than other algorithms, and it can tolerate approximate or even noisy design evaluation. In particular, it can operate in non-connected domains, which is an extremely useful property for our problem. In fact, as noted above, we are maximizing a log-likelihood function, and the possibility of getting a negative argument should be taken into account.[6] Another important feature of a Genetic Algorithm is that it can be efficiently parallelized. Therefore, it can potentially take full advantage of a GRID based application. In fact, by distributing the total amount of the calculation burden on several computation elements (CE), it is possible to reduce the machine time as explained in detail in the next subsections.

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[6]It is well know how any deterministic optimization method, which needs to compute the gradient of the objective function, cannot handle such a problem.

4.2. *Genetic algorithm*

Genetic algorithms are search algorithms based on the mechanics of natural selection (see [24] for a complete reference). Following Poloni and Pediroda [34], a genetic algorithm can be described with a pseudo-code structure such as

```
do ng generation
    do nind individuals
            translate bits into variables
            compute objective
    end do
    do some statistics on the population individuals
    do Create a new population:
        by cross over:
        select individuals
        and reproduce
        by mutation:
        select individuals
        and mutate
    end do
end do
```

The key points of a GA are the operators used for selection and reproduction that are crucial for the robustness and the efficiency of the algorithm.

In order to understand the mechanism of a GA, we illustrate in the next subsection some of the operators and functions used in our implementation.

4.2.1. *Coding*

To start the algorithm, it is necessary to define the initial population, which is any collection of solutions that could reasonably span the whole solution space. In order to perform this task, we generated a random sampling over that space, as explained in Montgomery [31] and Del Vecchio [15].[7] Each design variable is then coded in a finite-length string; traditionally, GAs use binary numbers to represent such strings: a string has a finite length, and each bit of a string can be either 0 or 1. For real function optimization, however, it is more natural to use real numbers: the length of the real-number string corresponds to the number of design variables (cf. [14]). We adopted this coding technique. After the initial population is generated, the process of selection is implemented. The selection (reproduction) operator selects chromosomes, according to their fitness function values, to choose a new generation. In the selection procedure, the well-fitted individuals have more chances to be selected. It is worth noting that it is not a deterministic choice: even solutions

---

[7]It is important to note that, in order to avoid local optimum solutions, the size of the population has to be two to four times the size of variables, as noted by Rao [35].

with a comparatively low fitness may be chosen, and they may reveal good choices in the evolution of the algorithm (see [33]). The three selection techniques usually used are:

Roulette wheel is the first and most popular operator. A selection probability proportional to its fitness is assigned to each individual in the population. The operator is robust but computationally intensive; moreover, it could cause premature convergence if no scaling of fitness is applied.

Tournament overcomes the problem of fitness scaling, and it is considered more efficient and robust than roulette wheel. The characteristic of a tournament is to keep the best of a group of individuals randomly selected. In our implementation we used this operator.

Local Geographic Selection elsewhere named as step-stone island model is a particular case of Tournament Selection. The n-size individuals participating in the tournament are not selected randomly in the population but through a local random walk in the neighborhoods of a particular individual, given that the population is distributed in an N-dimensional grid.

Next step in the GA is to fill up the new generation. The main way to perform this task is through the cross-over operator. Amongst the cross-over operators the one with the highest search robustness is the *two point cross-over*; in this operator, two points are randomly chosen, and the genetic materials (i.e., the design variables) are exchanged between the parent variable vectors, as shown below:

A		**0**	**0**	**1**	**0**	**1**	**1**	**0**	**1**		1	1	**1**	**0**	**1**	1	1	0	A′
B		1	1	**1**	1	0	**1**	1	0		**0**	**0**	1	1	0	**1**	**0**	**1**	B′

Another powerful cross-over operator has been implemented: the *directional cross-over*; it assumes that a "direction of improvement" can be detected by comparing the fitness value of two reference individuals. The schema is shown below:

(1) for all individuals i,
(2) select individual i_1, select individual i_2,
(3) create the new individual as

$$\bar{x} = \bar{x}_i + S \cdot \text{sign}(F_i - F_{i1}) \cdot (\bar{x}_i - \bar{x}_{i1}) + T \cdot \text{sign}(F_i - F_{i2}) \cdot (\bar{x}_i - \bar{x}_{i2}),$$

where S and T are random numbers in the interval $[0, 1]$ and F is the value of the fitness function for the corresponding vector of variables $\bar{x}$.

Finally in order to enhance population diversity, a mutation operator is performed. A mutation is a random change in the genetic material of a single individual; it is applied to genes by changing them with a low probability, P_m. In our case, a mutation means switching a bit 0 to 1 and vice versa. This operator enables the optimization to get out of local minima.[8] A mutation algorithm can be described

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[8]An intuitive characteristic of the mutation operator is that the higher the probability of mutation the more the search process functions like a pure random search.

as follows:

A′   1   1   1   0   1   1   1   0 $\longrightarrow$ 1   1   1   0   **0**   1   1   0   A″

4.3. *Results*

It is likely that in the close future, GRID technology will allow portfolio managers, as well as researchers in finance, to use plenty of computational resources in order to simulate complex models. This means that it will be possible to solve time expensive problems by drastically reducing the initial investment on computing or storage elements. To our knowledge, the model we proposed in this paper is the first step toward this direction, and whether it is suitable for a real case scenario depends on its accuracy and relative speed compared with other approaches. In this section, therefore, we address the in-sample accuracy of the estimated risk sensitivities.

First, it is interesting to assess the capability of the employed optimization algorithm. Figure 1 helps analyze the computational performance of the Genetic Algorithm. It shows, in terms of the absolute value reached by the optimized likelihood function, the gain obtained in increasing the generations size. Clearly the Genetic Algorithm has an asymptote that is reached, in our test, at 1000 generations. The maximum value attained for the log-likelihood function is 6581.9. It is worth noting that, with 500 generations, the attained value is 6447.88; thus, while diminishing the number of generations by a factor of 2 would certainly help in speeding up the algorithm, the loss of accuracy is only of about 2%. Thus, if a practitioner
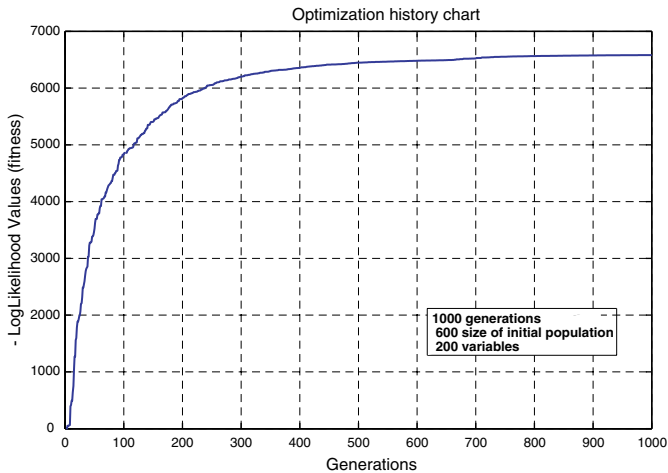

Fig. 1. Genetic algorithm performance. This figure plots the performance, in terms of absolute value of the obtained likelihood function, with respect to the number of simulations employed. The GA is employed on the optimization process of a 50 stock portfolio, randomly selected, with a time span of 33 years. All the data are from the CRSP database.

wants to adopt our method in order to estimate time varying risk sensitivities on a wide range of stocks portfolios by using the GRID technology, he/she knows that he/she can reach his scope with lower resources expenditure (i.e., by booking less computational resources).

Table 2 presents parameters' estimation in to the selected stock portfolios. By analyzing these results, we can draw some preliminary insight into the goodness of fit of the proposed model. First, the model seems to be able to explain a consistent part of the analyzed stock returns, with an R^2 that ranges from 0.65 for the Money

Table 2. Parameter estimation.

	Qtn 1	Qtn 2	Qtn 3	Qtn 4	Qtn 5
Panel A: size portfolios					
$\overline{\beta}$	1.099	1.311	1.292	1.181	0.965
	(0.054)	(0.041)	(0.029)	(0.015)	(0.006)
α	0.850	0.817	0.839	0.785	0.320
	(0.020)	(0.031)	(0.030)	(0.061)	(0.131)
σ	0.045	0.040	0.015	0.005	0.003
	(0.003)	(0.006)	(0.002)	(0.001)	(0.001)
R^2	0.667	0.818	0.902	0.949	0.985
*Panel B: E-P portfolios*******					
$\overline{\beta}$	1.115	1.013	0.925	1.002	1.011
	(0.025)	(0.032)	(0.019)	(0.031)	(0.031)
α	0.880	0.830	0.636	0.697	0.589
	(0.045)	(0.029)	(0.148)	(0.053)	(0.108)
σ	0.003	0.015	0.011	0.037	0.051
	(0.001)	(0.004)	(0.002)	(0.007)	(0.009)
R^2	0.899	0.903	0.863	0.803	0.748
Panel C: D-P portfolios*					
$\overline{\beta}$	0.920	0.953	0.812	0.965	0.412
	(0.030)	(0.021)	(0.026)	(0.024)	(0.142)
α	0.841	0.750	0.801	0.710	0.972
	(0.026)	(0.032)	(0.028)	(0.054)	(0.008)
σ	0.017	0.018	0.019	0.025	0.014
	(0.003)	(0.002)	(0.004)	(0.004)	(0.003)
R^2	0.916	0.928	0.895	0.869	0.830
	Manuf	Utils	Shops	Money	Other
Panel D: industry portfolios					
$\overline{\beta}$	1.013	0.891	1.185	0.870	1.070
	(0.050)	(0.041)	(0.047)	(0.032)	(0.025)
α	0.935	0.898	0.916	0.756	0.758
	(0.016)	(0.021)	(0.015)	(0.045)	(0.038)
σ	0.009	0.015	0.013	0.036	0.023
	(0.003)	(0.007)	(0.002)	(0.004)	(0.004)
R^2	0.883	0.934	0.848	0.653	0.884

Note: This table reports the estimated parameters of the analyzed stock portfolios. The portfolios are from the Kenneth French website. All returns are monthly value weighted.

*Sample starting July 1927.

**Data available from July 1951.

industry portfolio to 0.98 for the highest quintile SIZE portfolio. This result is consistent with a relevant strand of the literature, started by Jagannathan and Wang [27]. In their paper a conditional capital asset pricing model with time varying betas and market risk premiums is tested. Using returns on human capital and aggregate wealth they are able to explain 57% of cross sectional stock returns variability. Some other features of the presented panels are worth noting. In Panel A, where the SIZE portfolios are analyzed, the explanatory power of the model is increasing in size, with an increment of 30 percentage points in the statistics from the smallest to the biggest portfolio. This result is well documented in literature (see for example [1, 18, 19]). Unsurprisingly, a related pattern is followed by the estimated volatility parameters for the SIZE portfolios: where R^2 is higher, the volatility tends to be smaller within an order of magnitude in the first quintile versus the last quintile. Similar results can be inferred from Panels B and C, where the estimated parameters are presented for E-P and D-P portfolios, respectively. In these cases, even if the R^2 range is narrower, the variance of the growth stock portfolios seems to be better explained by the model. Again the same pattern for the volatility of the unobservable process is founded. Finally, Panel D presents the results for industry based portfolios. While the model performs well in most of the analyzed portfolios, it is worth noting its relative lack of accuracy for the Money portfolio with respect to the other industries.

Further insights from the estimated processes can be inferred by analyzing the parameters obtained for different portfolios. While analyzing all the estimates would add few information for the readers, it is important to focus on selected features that we can gather from the mean reverting parameters and the long term mean. In particular, the High D-P portfolio (cf. Panel C, last column) displays a long term parameter of 0.4 coupled with an high mean reverting coefficient and a relatively low conditional volatility of beta[9] (1.5% on an annual basis compared with a range from 3.1% to 6% for the other quintiles). Such a result can be interpreted as clear evidence of the less risky nature of high book to market portfolios, in line with the previous literature (see [20]). Even clearer is the effect on the SIZE portfolios. In fact, running the same simple calculations, we obtain an annual conditional volatility of less than 1% for the beta process of the Big portfolio. This result, coupled with a long term mean less than 1%, confirms the cited SIZE effect (cf. [1, 18, 19]) especially when compared with the values obtained for the small portfolio. SIZE and Book to Market effects are confirmed also by an analysis of Fig. 2: by comparing the plots in Panel A for the SIZE portfolios and Panel C for the D-P portfolios, it is evident how the estimated processes for the betas display patterns easily interpretable as riskier for the low Book to Market and small portfolios, respectively.

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[9]Conditional volatility is obtained from the unconditional estimates by simply applying $\sigma^2_{\text{cond}} = \sigma^2_{\text{uncond}*}(1 - \alpha^2)$.
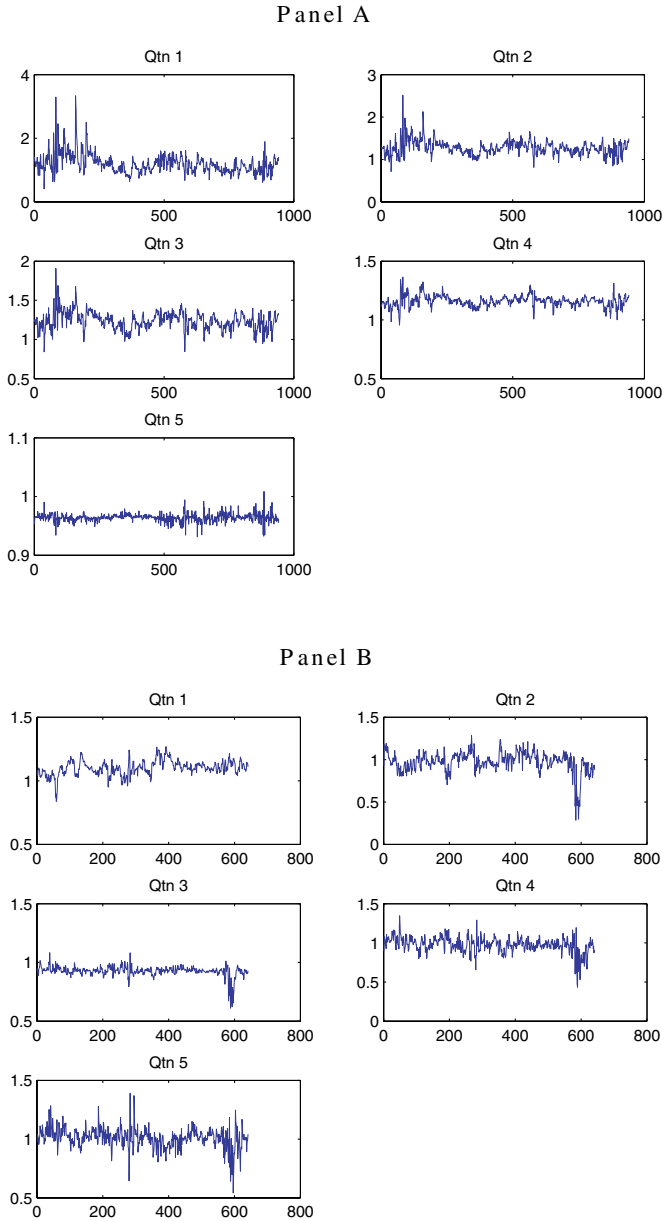
Fig. 2. Plot of estimated process. This figure plots the estimated path of the beta processes. Panel A through D show respectively the estimated processes from SIZE, E-P, D-P, and Industry portfolios. For the E-P portfolios the sample size goes from July 1951 to December 2004, while for the D-P portfolios it goes from July 1927 to December 2004. The remaining data are from July 1926 to December 2004.
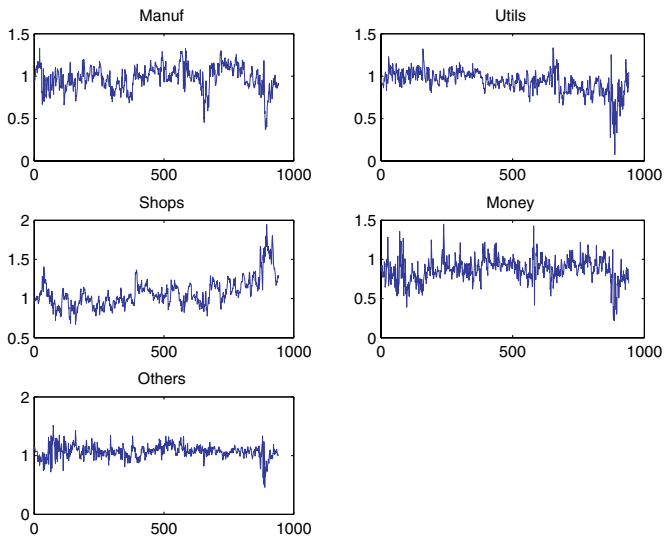
Panel C
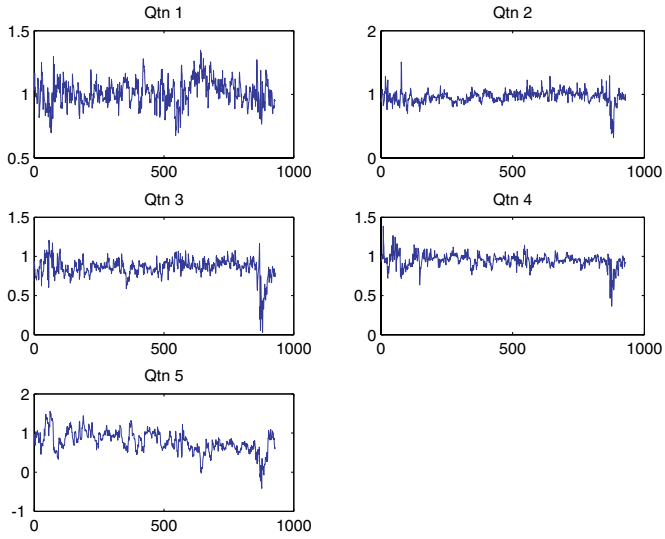
Panel D

Fig. 2. (*Continued*)

5. An Application to Risk Management

In this section we apply the estimation method proposed in Sec. 4.1 to a simple Value a Risk (VaR) exercise. We processed our data using a GRID environment implemented in a national facility as part of the research project EGRID. By comparing a VaR, based on the time varying model proposed above, with more classical approaches we can shed some light on the relative accuracy of our approach as well as on its gains in terms of computational time.

5.1. *EGRID Project*

As explained in detail by Leto *et al.* in [30], the EGRID project is a research project funded by MIUR.[10] The aim of the project is to investigate the role of GRID technologies in the field of complex systems applied to economics and finance. The MIUR evaluation committee assigned to the EGRID project a further specific task: to implement a GRID infrastructure allowing geographically distributed scientific communities involved in these projects to share economic and financial data as well as applications. A preliminary version of this infrastructure was released on October 9, 2004: it is based on European Data Grid (EDG) middleware and is hosted as an independent Virtual Organization (VO) within INFN-GRID.[11]

The EGRID project managed to successfully implement the facility with the following features:

- the possibility to handle approximately 1 GB of data coming from various stock exchanges;
- data privacy and security, i.e., the access to this resource had to be secured, authorized, and authenticated;
- the capacity of checking availability of machines to distribute the computing load.

In the Risk Management exercise proposed in this section, we take advantage of the GRID infrastructure, treating our application as multithread. Loosely speaking, multithreading can be defined as a programming technique that enables an application to handle more than one operation at the same time. A main application has been created and launched in a "server machine": this program manages the Genetic Algorithm and constantly listens to a port for communication with other programs running in "client machines" inside the GRID (cf. Fig. 3). Each client application elaborates a particular configuration (a genetic individual of the generation) as required by the server. In this setting, the most challenging task was to make sure that multiple threads did not interfere with each other in an undesired way. In a Risk Management setting, the VaR indicates, in percentage terms, the

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[10]Ministero dell'Istruzione, Università e Ricerca: Italian Ministry of Education, University and Research.
[11]The national computing grid infrastructure of INFN (Istituto Nazionale di Fisica Nucleare: Italian National Institute for Nuclear Physics).
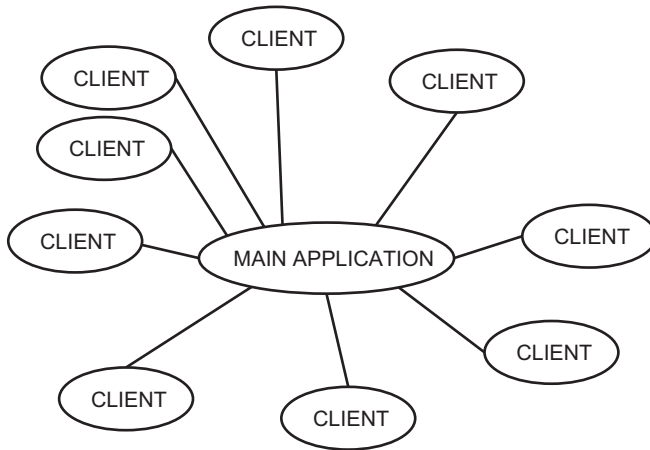
Fig. 3. A simple representation of a multithreading application.

maximum probable loss on a given portfolio, referring to a specific confidence interval and time horizon. Historically, the VaR literature has been evolved following two main approaches: parametric and non-parametric models (see [28] for a complete reference). In the latter class of models we can pinpoint full valuation models as Historical Simulation and Monte Carlo Simulation. The Historical Simulation uses past empirical distribution of returns in order to simulate the probability distribution of future returns. The VaR is then calculated as the chosen percentile of the simulated distribution. On the contrary, Monte Carlo Simulation models are based on a simulation of predetermined risk factors which allow the risk manager to calculate the return distribution. Again the VaR is determined as the relevant percentile of the obtained distribution. On the other hand, the parametric approach is based on the estimation of a single parameter and has imbedded the simplifying assumptions of normal distribution of returns and linearity of portfolio returns with respect to the considered risk factors. These two hypotheses imply a normal distribution for portfolio returns. Consequently, it is possible to describe the returns' distribution simply with the first two moments, and thus, the VaR can be calculated using the relevant percentile from a standard Z-distribution. In our empirical exercise we use a simple parametric approach, based on the beta estimation performed in Sec. 4, for evaluating several stock portfolios of the US market. Using the model proposed in Eq. (2.4), it is straightforward to define the variance of a portfolio as

$$\sigma_p^2 = w'\beta\beta'w\sigma_m^2 + w'\Sigma w, \tag{5.1}$$

where w indicates a column vector of assets weights, β is a column vector of the estimated risk sensitivities, σ_m^2 is the variance of the market factor, and Σ is the diagonal variance–covariance matrix of idiosyncratic disturbances. It is a well-known result that, as the number of assets in portfolio increases, the idiosyncratic risk

becomes negligible. Thus, for a well-diversified portfolio we can calculate the Value a Risk as

$$\text{VaR} = \alpha_z \sqrt{w'\beta\beta'w\sigma_m^2}\sqrt{t}, \qquad (5.2)$$

where α_z indicates the relevant percentile of the Z-distribution and t is the chosen time horizon. The proposed VaR measure is tested on a set of equally weighted portfolios based on the SIZE, E-P, D-P, and Industry portfolios. The betas are estimated from the time varying sensitivities as proposed above, while the volatility of the market is simply calculated as the historical standard deviation of the market index returns. The chosen confidence interval is 5% one side losses, and the selected time horizon is one month. To assess the accuracy of the calculated Value at Risk we perform a Proportion of Failure (POF) test based on Kupiec [29], calculated as

$$\text{LR} = -2\ln\left(\frac{p_0^x(1-p_0)^{(n-x)}}{p^x(1-p)^{(n-x)}}\right), \qquad (5.3)$$

where p_0 is the probability of an exception implied by the chosen confidence interval, n is the sample size, x is the actual number of exception, and p is the Maximum-Likelihood estimator x/n of p_0. Basically, this test performs a Likelihood-Ratio with 5% level, based on the number of exceedences in any given sample, where the null hypothesis is that the estimated value for the exceedences matches its exact value. Given its definition, the test is asymptotically χ^2 distributed with one degree of freedom; thus, if the value of the test statistic exceeds the critical value of 3.84, the Value at Risk model can be seen as not reliable with a 95% confidence level. Table 3 shows the performance of the Value at Risk measure via a backtesting. The obtained results are more than encouraging. In all the analyzed portfolios, the POF statistic is well below its critical value. Thus, we do not reject the null hypothesis of a reliable VaR measure. In order to put our results in perspective, we estimate both the same VaR measure with more classical approaches such as an Exponential Moving Average (EWMA) estimation of the market volatility, and a full parametric Value at Risk following the procedure proposed by Riskmetrics.[12] In the whole sample of the analyzed portfolios, employing the EWMA volatility does not change the accuracy of the proposed VaR measure. More importantly, for both D-P and Industry portfolios (Panels C and D, Table 3), the VaR measure based on the model outperforms the full parametric VaR measure.

Furthermore, Fig. 4 allows us to compare the performance of the proposed VaR model in a time series perspective. The left column shows the actual returns with a VaR loss band calculated with the Full Model approach while the right column shows the loss band calculated with the Full EWMA approach. It is clear how both approaches produce a consistent bound that would allow a risk manager to eventually correctly allocate reserve capital. Furthermore, the relative higher reaction of

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[12]For a complete reference see http://www.riskmetrics.com.

Table 3. Value at Risk backtesting.

	Expected	Actual	LR test
Panel A: size portfolio			
VaR Full Model	44.000	40.000	0.404
VaR EWMA Model	44.000	40.000	0.404
VaR Full EWMA	44.000	40.000	0.404
*Panel B: E-P portfolio**			
VaR Full Model	29.000	28.000	0.040
VaR EWMA Model	29.000	27.000	0.156
VaR Full EWMA	29.000	27.000	0.156
*Panel C: D-P portfolio**			
VaR Full Model	43.000	43.000	0.005
VaR EWMA Model	43.000	42.000	0.051
VaR Full EWMA	43.000	34.000	2.331
Panel D: industry portfolios			
VaR Full Model	44.000	41.000	0.227
VaR EWMA Model	44.000	41.000	0.227
VaR Full EWMA	44.000	36.000	1.647

Note: This table reports the results of a Value at Risk back-testing on the analyzed stock portfolios. The portfolios are equally weighted based on the Kenneth French portfolios. All returns are monthly value weighted. The decay factor chosen for the Exponential moving average is 0.97, while its rolling window is five years.
*Sample starting July 1927.
**Data available from July 1951.

the Full Model bound to returns' changes can be noted, especially at the beginning of the analyzed sample (cf. Panel A versus Panel B, and Panel G versus Panel H).

To further assess the potential of a GRID structure in solving a Risk Management problem, we test our model on a portfolio composed of 50 stocks randomly selected from the CRSP database. Interestingly enough, with the use of the GRID infrastructure, we have obtained a reduction of computation time proportional, to a certain extent, with the number of available clients. In particular, we measure the performance of a GRID infrastructure on a cluster of eight nodes. The speed, shown in Fig. 5, Panel A, increases dramatically when three clients are employed, gaining 193-sec with respect to a single node, with a decrease of execution time from 426 to 233-sec, corresponding to a relative increase in performance of 45.3%. Employing five nodes gives a further improvement in the performance with a relative speed-up of 12%. For more than five nodes, the gain becomes negligible, with an average time of execution of 205-sec. To further investigate the performance of the employed GRID cluster, we separate the computation time of our exercise in time employed by the Genetic Algorithm, time employed for communication amongst nodes, and time for Kalman filter computation. Figure 5, Panel B, shows the employed time by the three pieces of the whole algorithm incrementally, displaying clearly where the bottlenecks arise. First of all, the GA is not parallelized in our implementation;
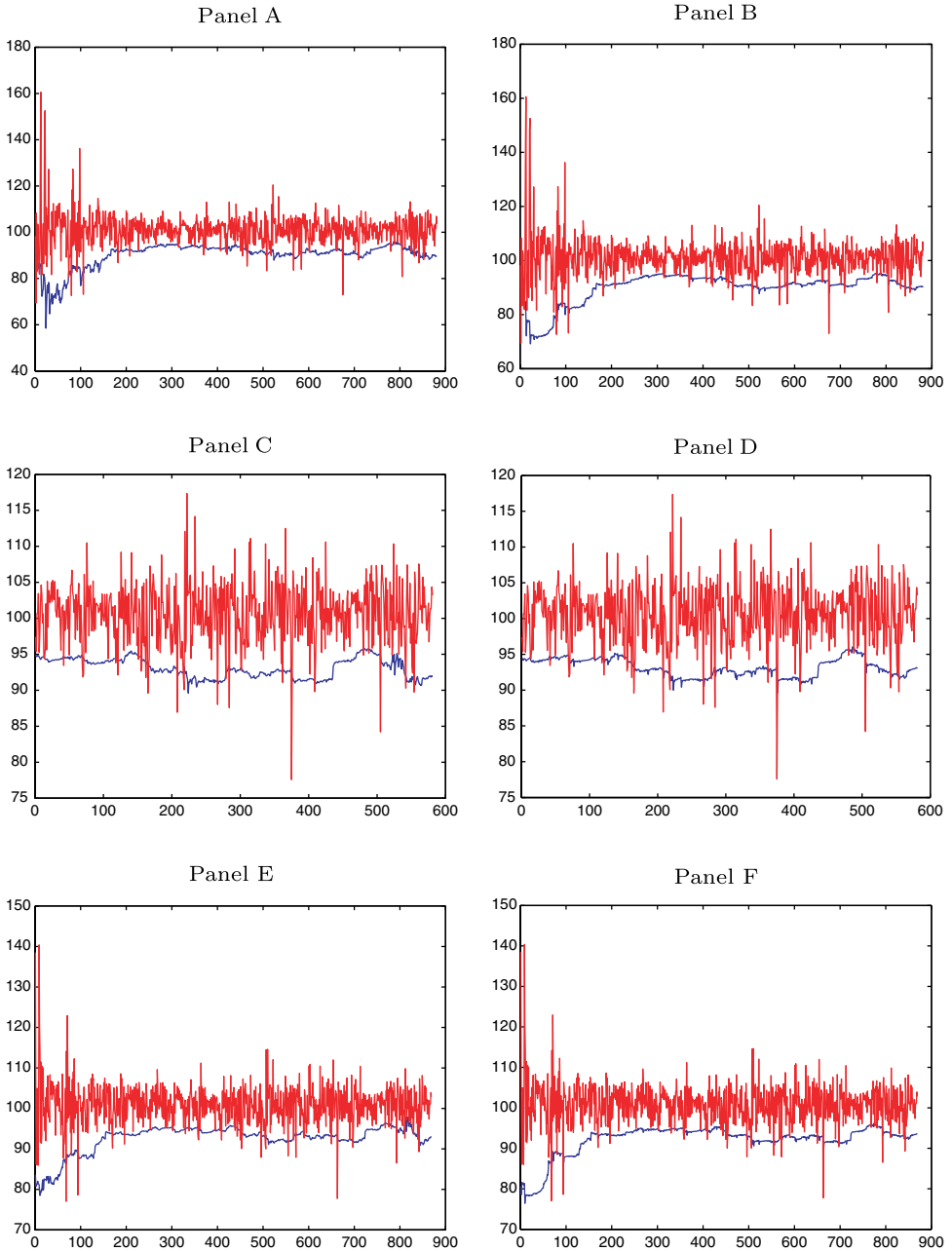
Fig. 4. Plot of Value at Risk backtesting. This figure plots the results from a Value a Risk backtesting. Portfolios are equally weighted and based on the Kenneth French portfolios. All returns are monthly value weighted. The decay factor chosen for the exponential moving average is 0.97, while its rolling window is five years. The left column shows the actual returns with a VaR loss band calculated with the Full Model approach while the right column shows the loss band calculated with the Full EWMA approach. Figures are referring to Size, E-P, D-P, and Industry portfolios, respectively.
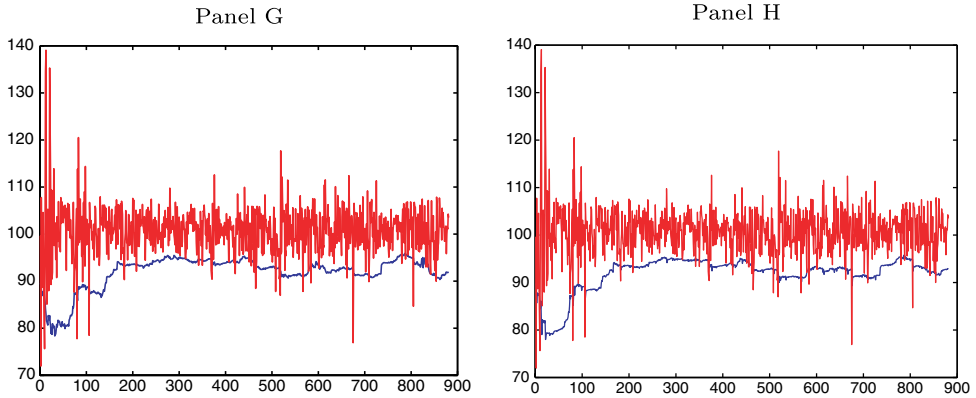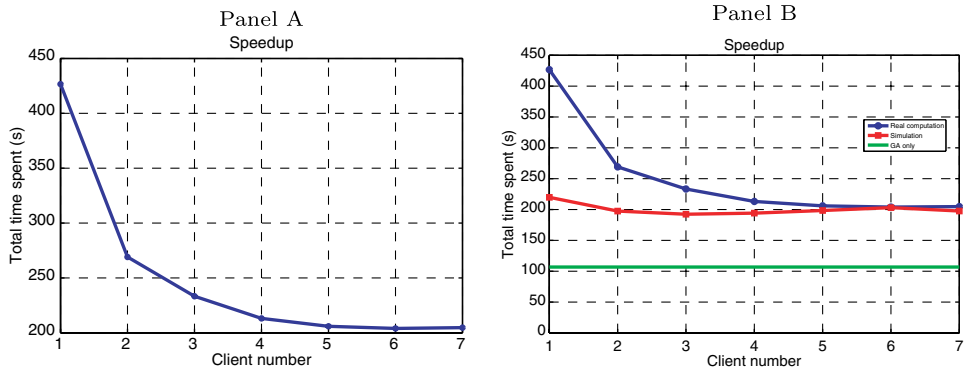
Fig. 4. (*Continued*)

Fig. 5. Performance gain on a GRID architecture. This figure plots the performance of an eight nodes, GRID cluster in performing a Risk Management application. The portfolio employed is generated randomly by picking 50 stocks from the CRSP database, with a time span of 33 years. Panel A shows the total computational time, while Panel B shows the time added, incrementally, to the total computational time by the Genetic Algorithm, the communication time, and the Kalman filter algorithm, respectively.

thus, it contributes with a constant amount of time to the entire time spent in executing the algorithm. Second, the communication time is also contributing nearly constantly to the total execution time, showing even a minor time increase when the number of clients increases. Third, the execution time employed by the Kalman filter is, as expected, gaining the most from the GRID architecture; this is mainly due to the parallel structure of its code, i.e., taking full advantage of a distributed computational capability. Finally, it is worth noting that the performance of the VaR is comforting, with a POF statistics well above the 5% critical value for all the randomly selected 50 stock portfolios.

6. Conclusion

The estimation of systematic risk has been one of the most studied topics in empirical finance. Historically, important research contributions were departing from the classical one factor constant beta model, exploring the two possibilities of multi-factors models and time varying sensitivities.

This paper refers to the latter stream of literature by estimating time varying sensitivities where the betas are supposed to be unobservable. By estimating the model via a Kalman filter augmented with a genetic optimization algorithm, we are able to explain a large part of the observed time series variance in several stock portfolios of the US market.

Given this estimate, we are able to calculate a Value at Risk measure, based on the proposed model, on a GRID computing architecture. In this context, the use of GRID computing offers an opportunity to enhance the solution of computationally demanding problems with decentralized data retrieval.

Our analysis aims at filling a part of this gap by showing how the use of GRID computing in a Risk Management application is well suited to and is able to provide an important efficiency improvement for financial applications. The results are more than promising in showing the accuracy of the proposed model coupled with the capability of the GRID architecture in dealing, in a reasonable amount of time, with CPU use intensive calculations and huge data retrieval queries.

Acknowledgments

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